



# Predictive Simulation of Helicopter Flight Controls and the V-Cycle

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# Overview

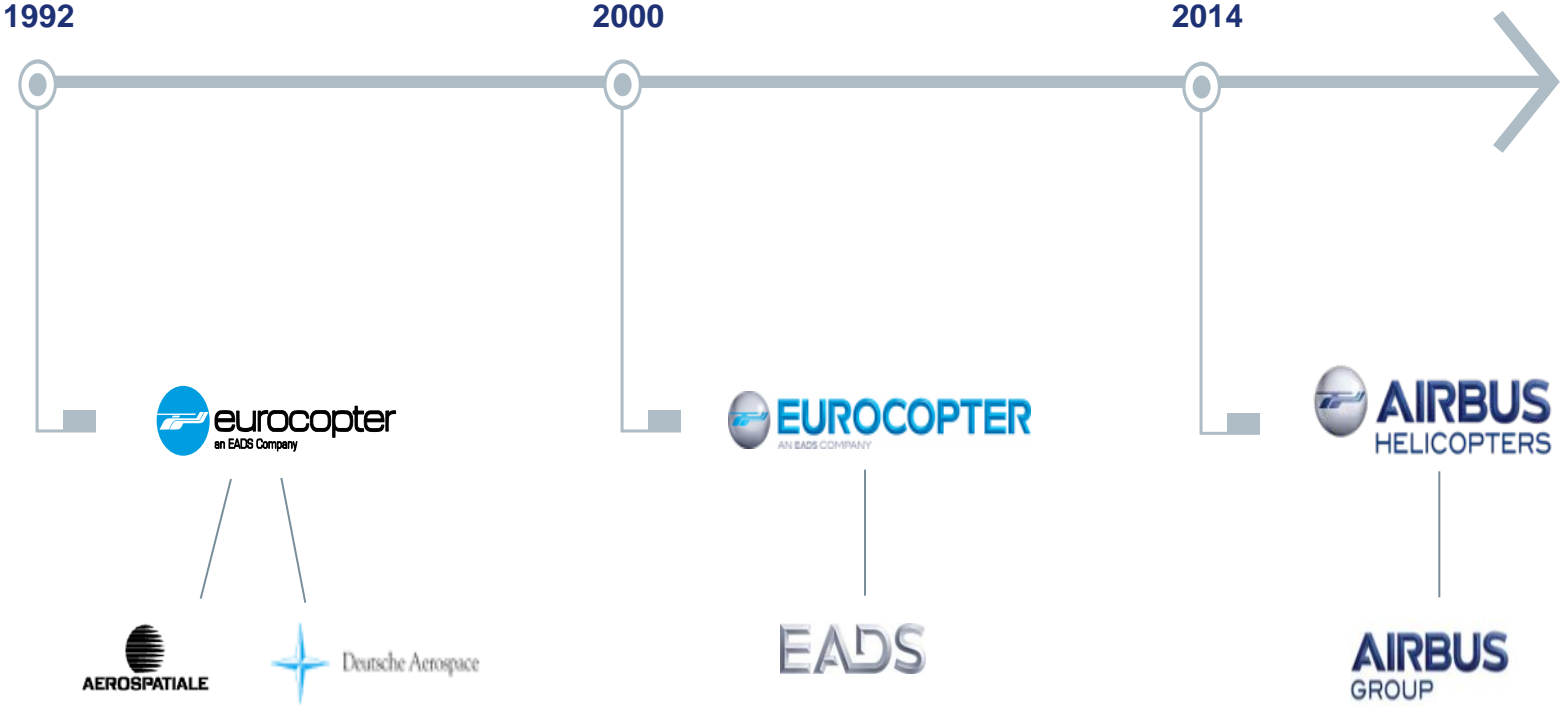
- Airbus Helicopters – who are we ?
- Model-based multi-level system engineering
  - Early validation, early verification → early redesign
- Equipment development
  - a more realistic V-cycle
- Examples
  - Flight control kinematics
  - Hydraulic servo
  - Electro-mechanical actuators
- „Cool“ Tools
- Conclusions

# Airbus Helicopters

Who are we ?

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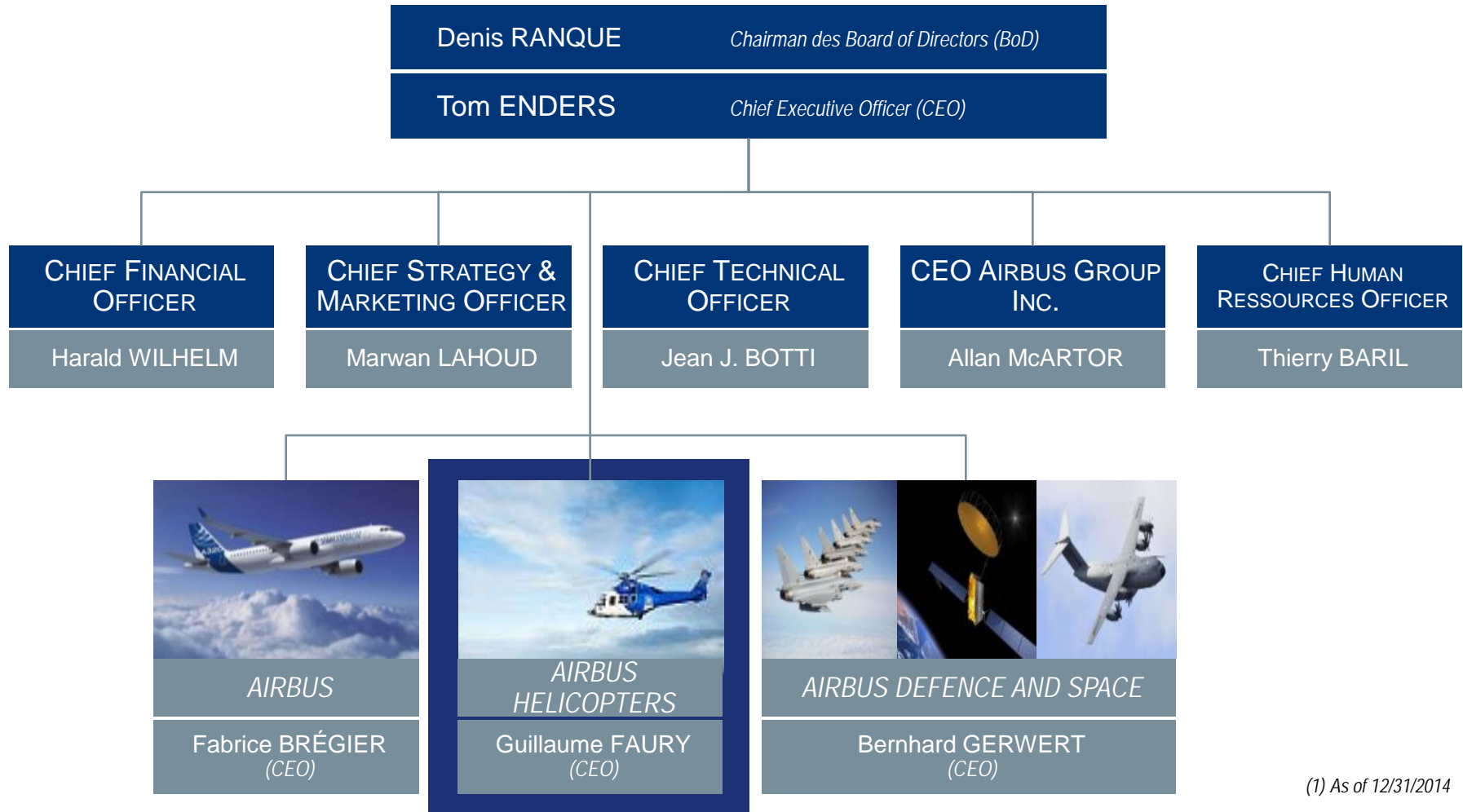
# From Eurocopter to Airbus Helicopters



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# Airbus Group top management structure (1)



(1) As of 12/31/2014

# Airbus Helicopters at a glance

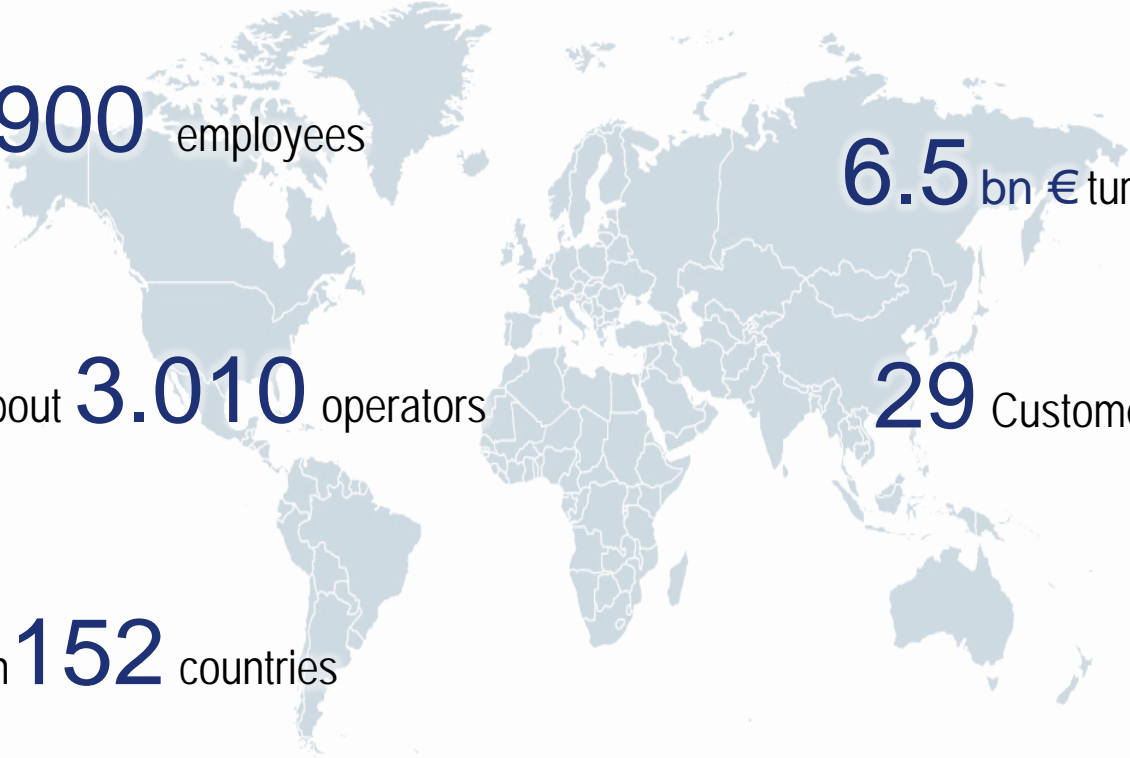
22.900 employees

6.5 bn € turnover in 2014

to serve about 3.010 operators

29 Customer Centers

in 152 countries



A unique global presence



# Airbus Helicopters: a global presence

**2,5 billion €**  
in orders in 2014

**29** Customer Centers

**7.600** employees  
(incl. Vector Aerospace)

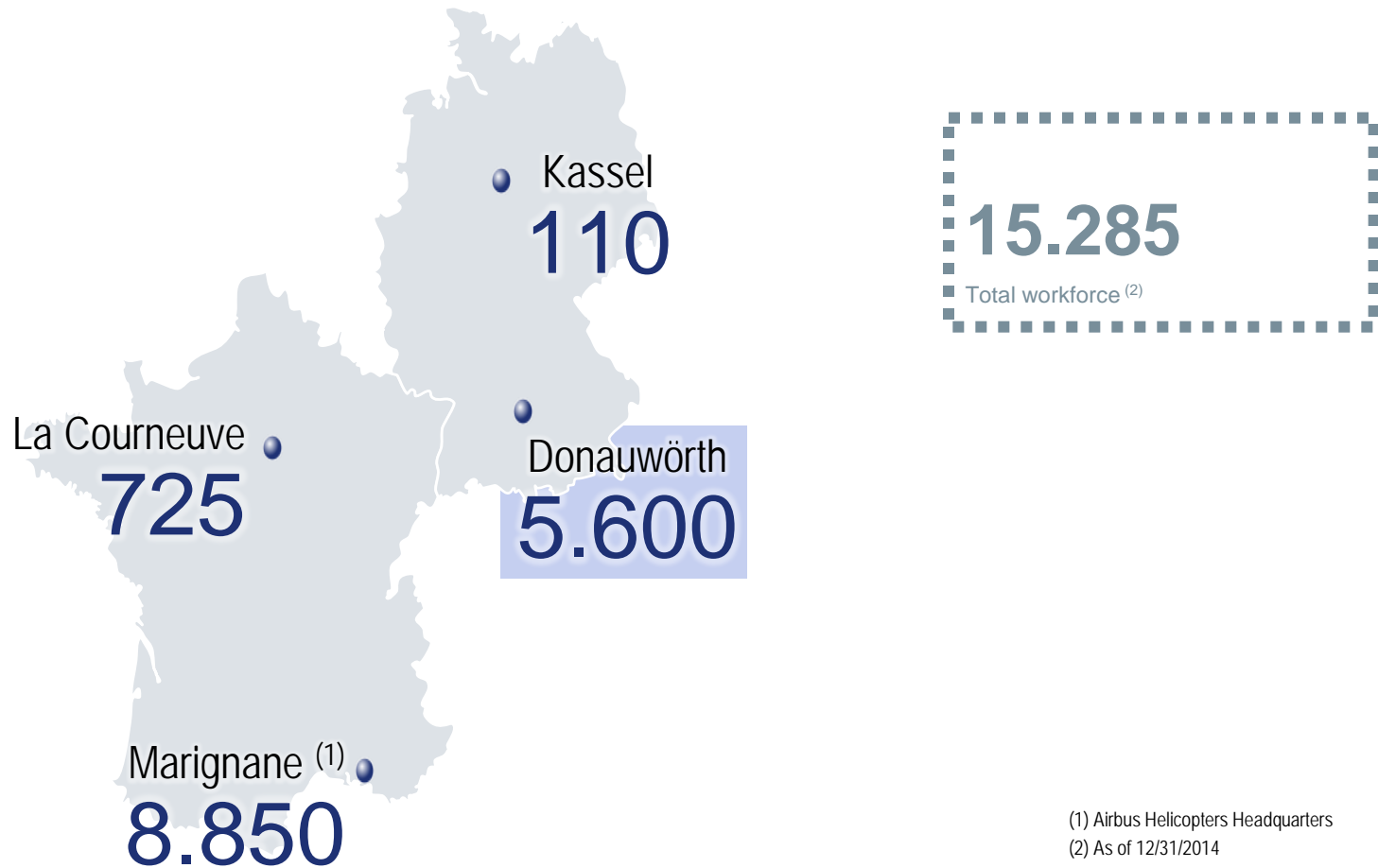
**70%**  
of customers







# Workforce and activities in the founding countries



(1) Airbus Helicopters Headquarters

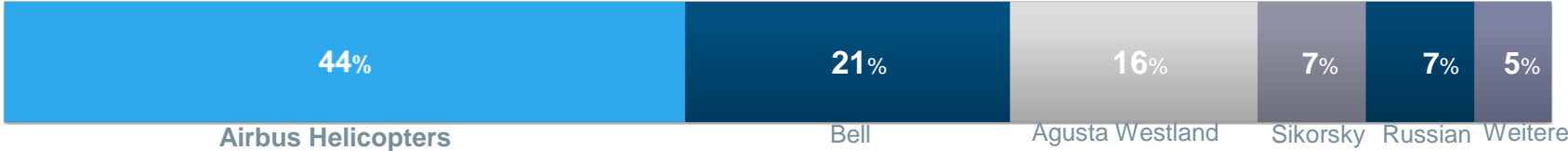
(2) As of 12/31/2014

# Airbus Helicopters priorities

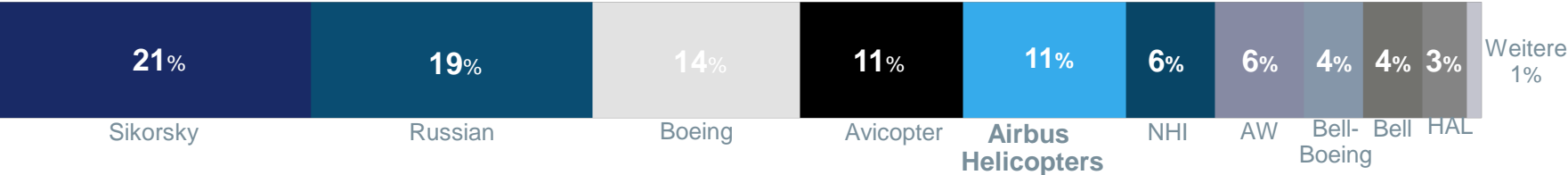


# Solid leader in the civil market; strong military market share

**Civil & parapublic market > 1,3 t**  
2014 market: **736 helicopters**



**Military market**  
2014 market: **869 helicopters**



# Supporting customers operating the most challenging civil missions



# The civil range

Single



H120  
(EC120)



H125  
(AS350)



H130  
(EC130)

Light twin



AS355



H135  
(EC135)



H145  
(EC145)

Twin medium



AS365



H155  
(EC155)



H175  
(EC175)

Medium/Heavy



AS332



H225  
(EC225)

# The military range

Light  
helicopter



Helicopter  
mean weight class



Helicopter mean weight/  
heavy class



Special helicopter



# The H160: the first member of Generation H

## NEW CANTED FENESTRON®

Increases performance levels, adds to passenger comfort thanks to excellent flight stability, and permits community-friendly sound levels.

## BLUE EDGE® BLADES

New blades increase performance levels, add to passenger comfort thanks to excellent flight stability, and permit community-friendly sound levels.

## FULL COMPOSITE AIRFRAME

Contributes to the robustness of the aircraft and lower maintenance.



## BIPLANE STABILIZER™

Contributes to agility with improved performance and exceptional handling.

## NEW GENERATION TURBOSHAFT ENGINE

More powerful than previous generation while reducing fuel consumption and CO<sub>2</sub> emissions.

## ELECTRICAL LANDING GEAR

Designed to allow more payload and helps to simplify aircraft maintenance.

# V-Cycle

## Development Process & Predictive Simulation

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# Predictive Simulation

Computational Fluid Dynamics (CFD)

Computational Structural Dynamics (CSD)

→ Finite Elements Method (FEM)

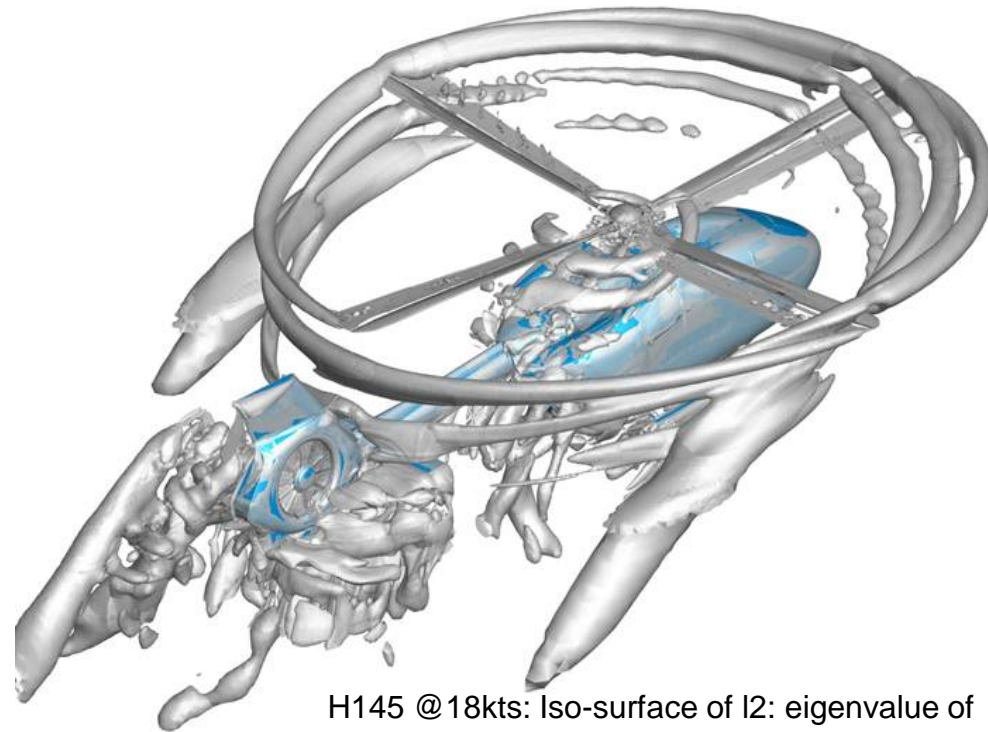
- Loads & stress analysis
- Eigenmodes & vibrations

Rotor aero-mechanics & helicopter performance

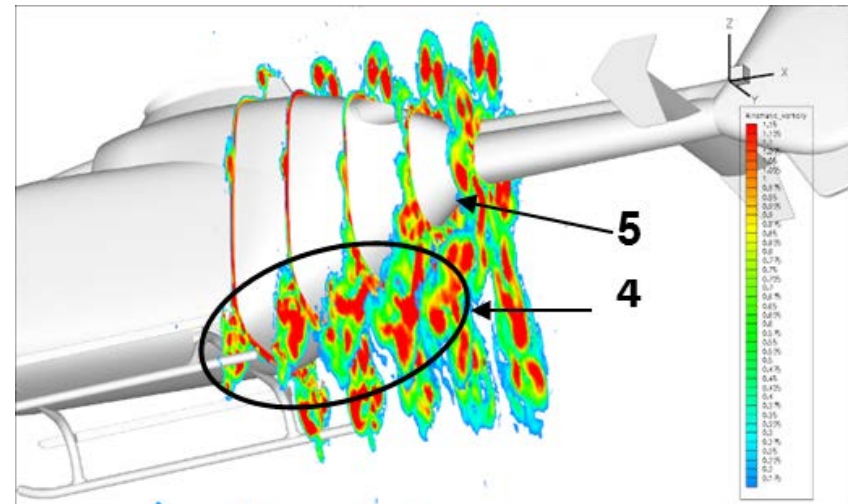
Flight law & Automatic Flight Control System (AFCS)

Multi-physics simulation of „systems“

- Kinematics of flight controls
- Hydraulic supply & actuation system
- Thermal heat conduction
- Electrical power supply system
- Electro-mechanical actuators

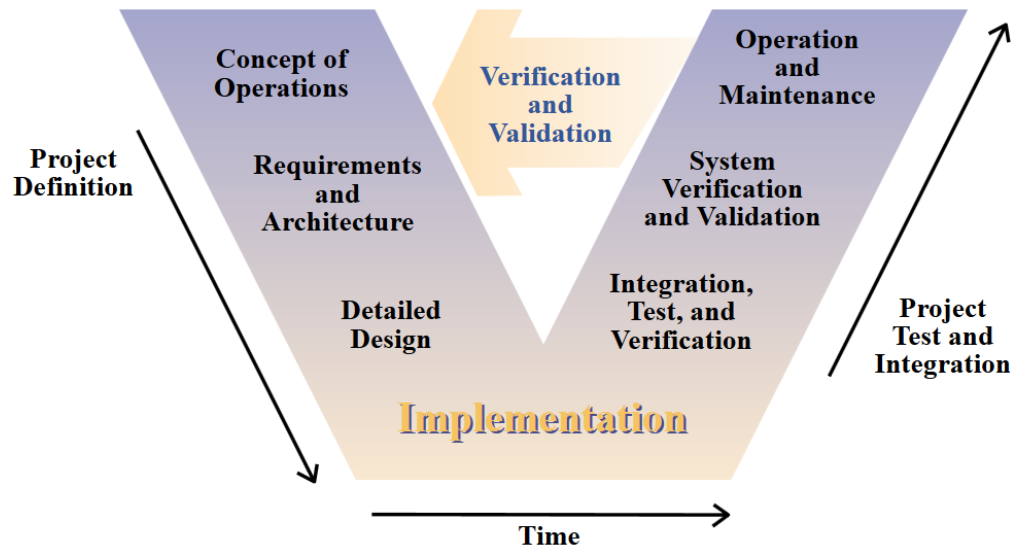


H145 @18kts: Iso-surface of I2: eigenvalue of the symmetry tensor of the velocity gradient



Wake of H135 fuselage:  
Kinematic Vorticity

# V-model of systems engineering process



Source: Wikipedia

# EUROCAE ED-79A / SAE ARP4754A AIRCRAFT OR SYSTEM DEVELOPMENT PROCESS

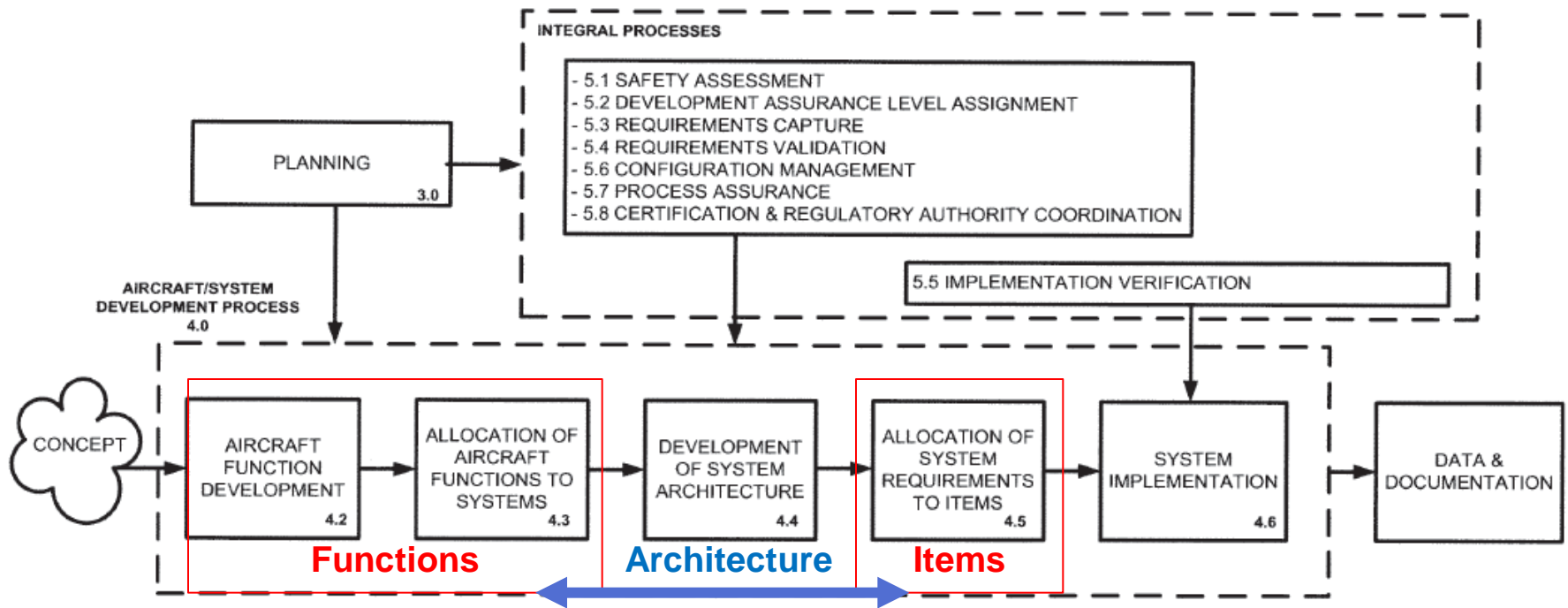


FIGURE 4 – AIRCRAFT OR SYSTEM DEVELOPMENT PROCESS MODEL

2 phases can be identified with two different types of development processes:

- **Function** development phase and
- **Item** development phase.

# EUROCAE ED-79A / SAE ARP4754A DEVELOPMENT LIFE CYCLE

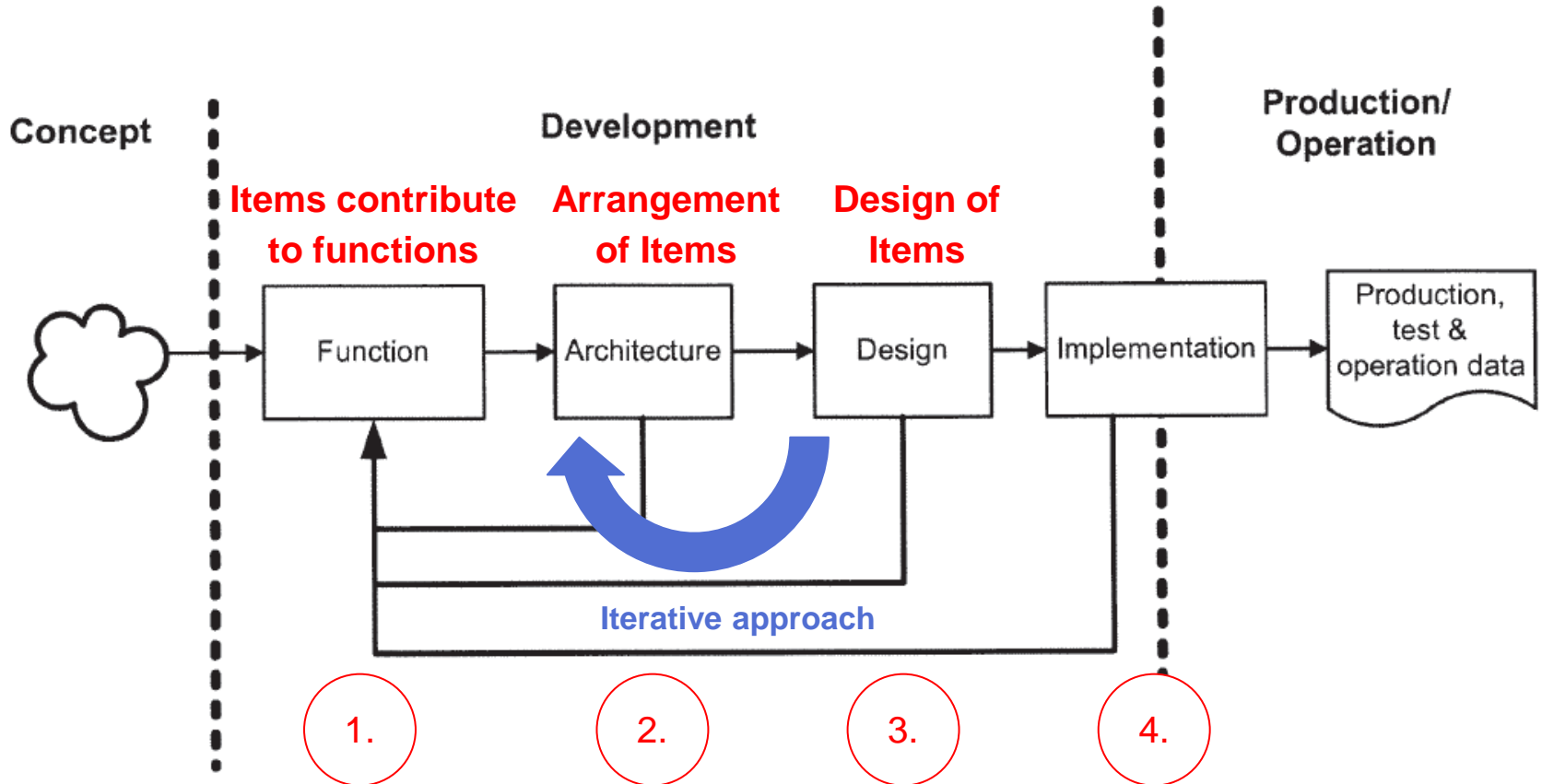
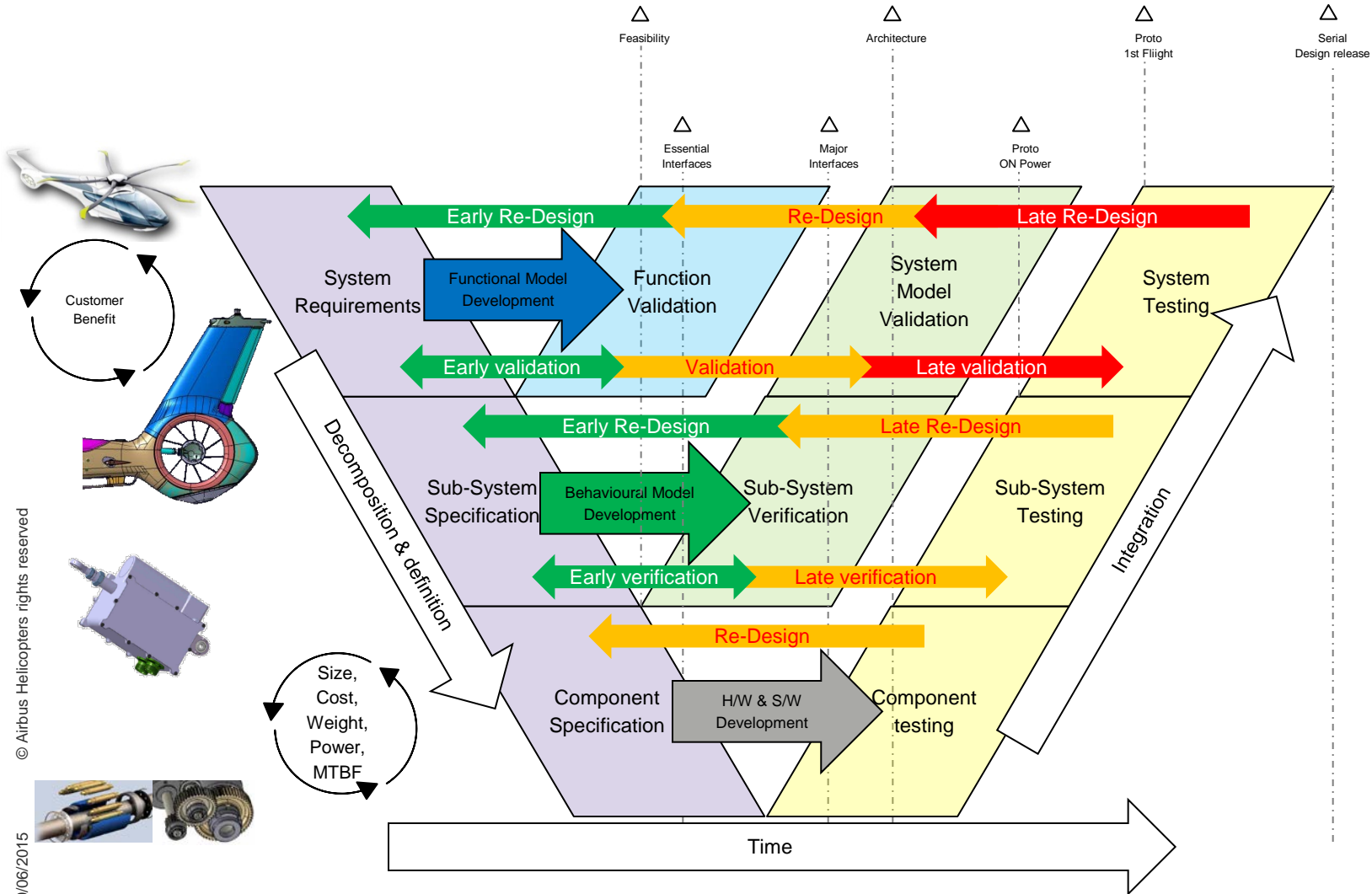


FIGURE 3 - DEVELOPMENT LIFE CYCLE

# Model-Based Multi-Level System Engineering



# Why Predictive Simulation ?

„Front-loading“ engineering design process

→ Risk reduction

→ Total cost reduction

Early validation & verification

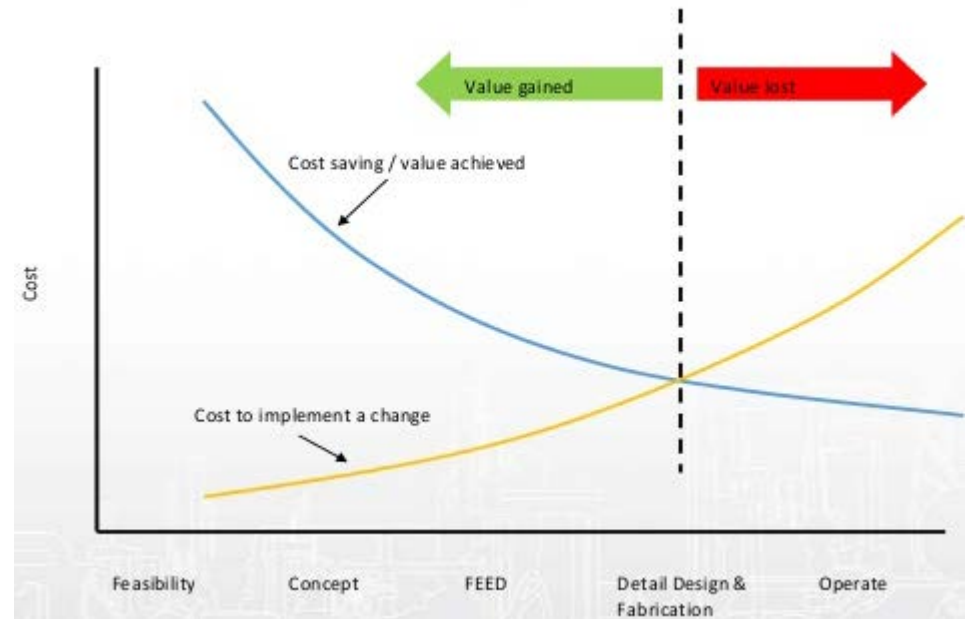
→ Avoid late & costly re-design

Feasibility & Pre-design

- Requirements
- Safety analysis: failure cases, degraded performance, ...
- Supplier proposals

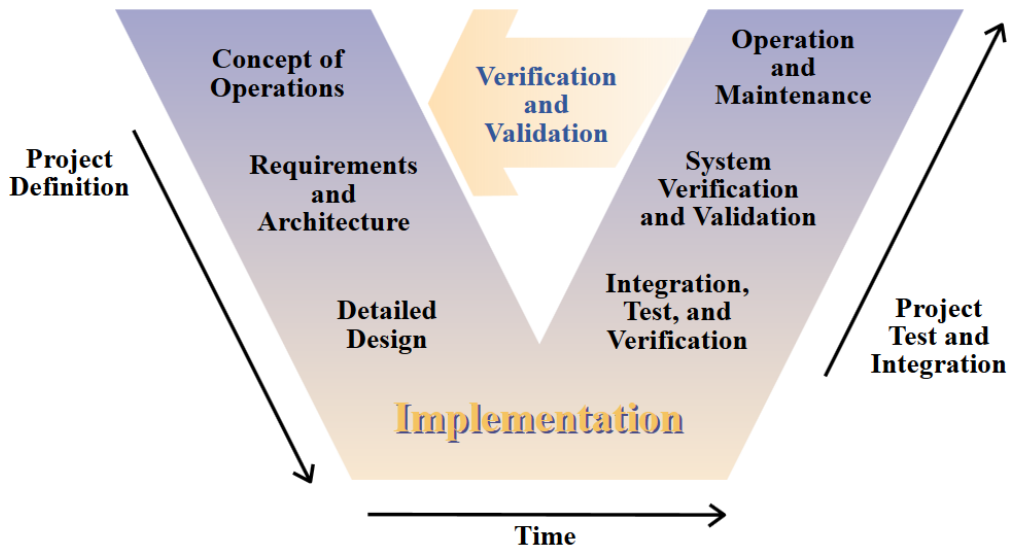
**Anticipate update loops for**

- **Corrective action**
- **Improvement & re-design**



Source: momentum engrg

# V-model of systems engineering process

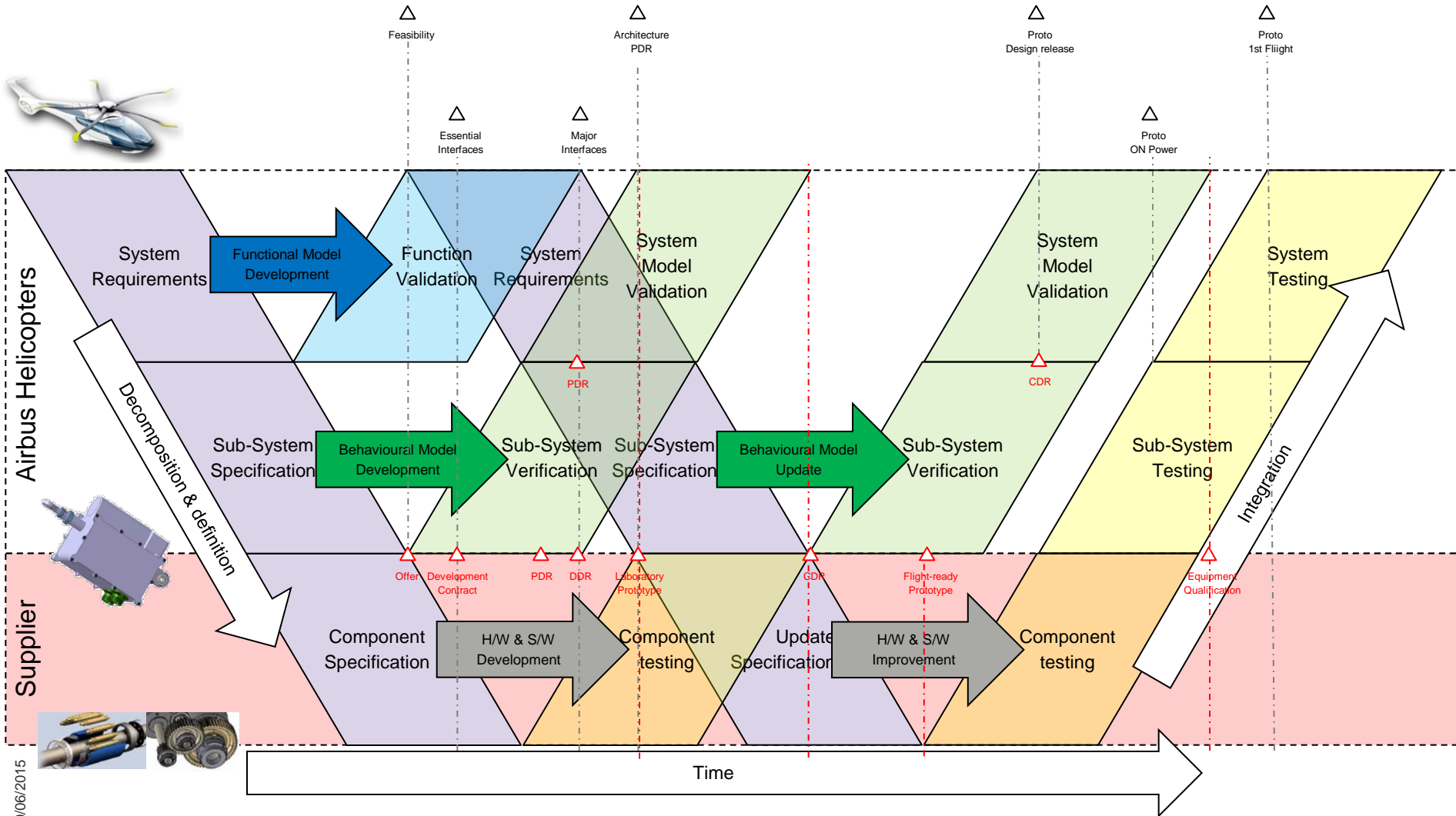


Source: Wikipedia

Iterative approach: function – architecture – design  
→ Update loops

**Predictive simulation to  
avoid „surprises“ late during test & integration**

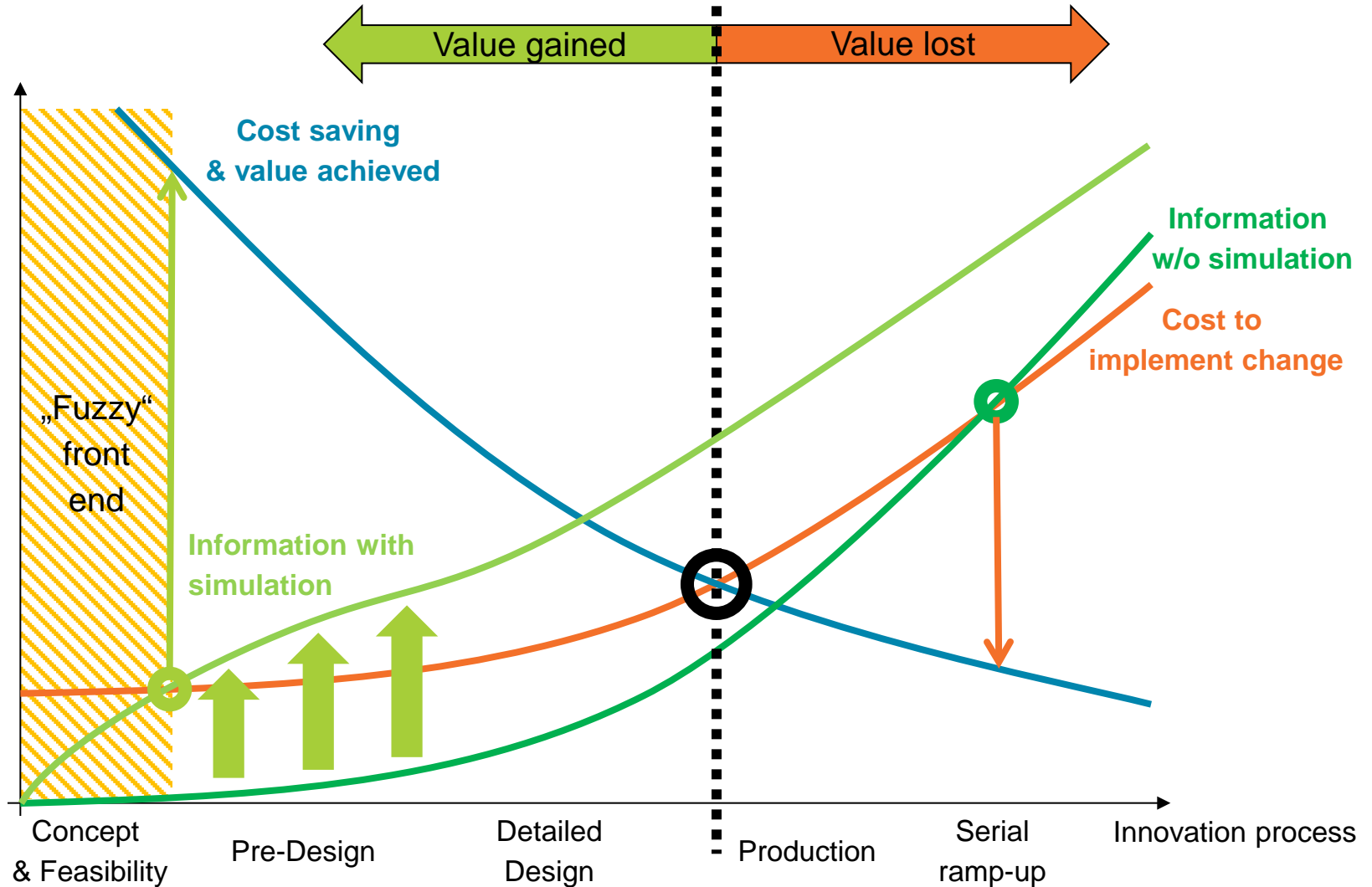
# Equipment Development - a more realistic V-cycle



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# „Fuzzy“ front end



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# Modeling of Flight Controls & Actuators

## Examples

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# Modeling of Flight Controls & Actuators

## Why simulation ?

- Predictive simulation of supplier equipment during feasibility & pre-design  
→ consolidate specification w/o info from suppliers
- Predictive simulation before equipment h/w testing & first flight of h/c prototype  
→ risk reduction

## Why time-accurate simulation ?

- Transient performance
- Nonlinearities: saturation, backlash, friction, ...
- Failure cases
- Systems integration
- Human-machine interaction

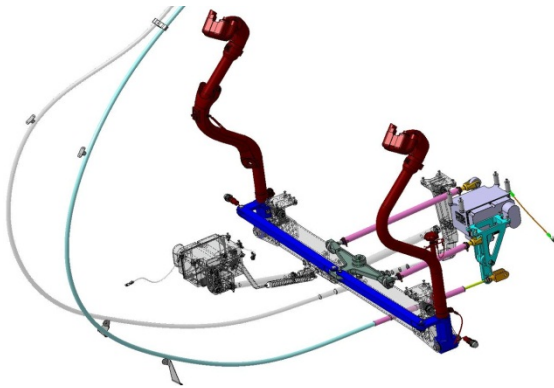
## Examples

- Flight control kinematics : pilot force feel
- Hydraulic servo actuator : phase & gain response
- Electro-mechanical actuator : braking travel in case of failure
- Electro-mechanical actuator : oscillation failure

# Flight control kinematics : pilot force feel

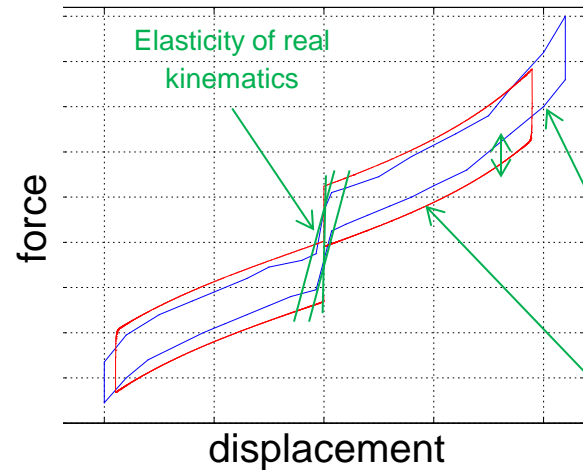
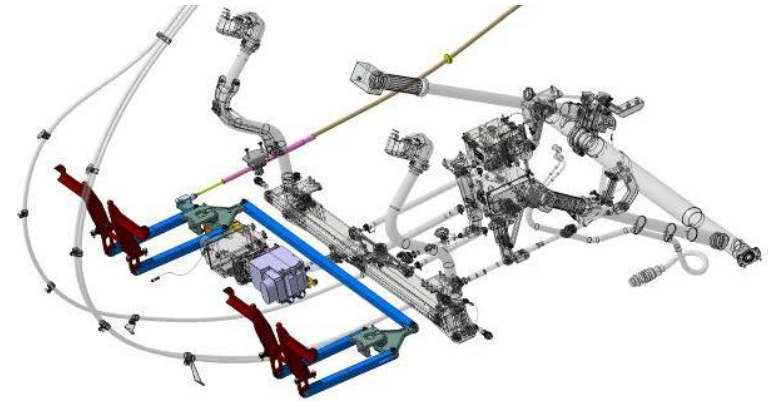
## Lateral Cyclic

- Centering spring
- Friction of kinematics (flexballs, ...)



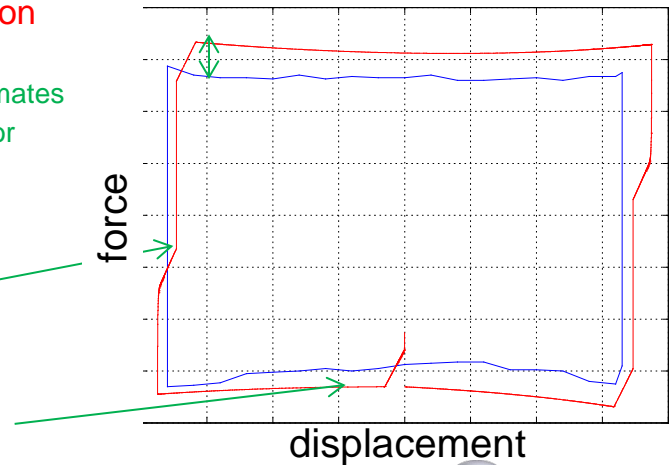
## Yaw (pedals)

- Friction characteristics (trim)



### Measurement / Simulation

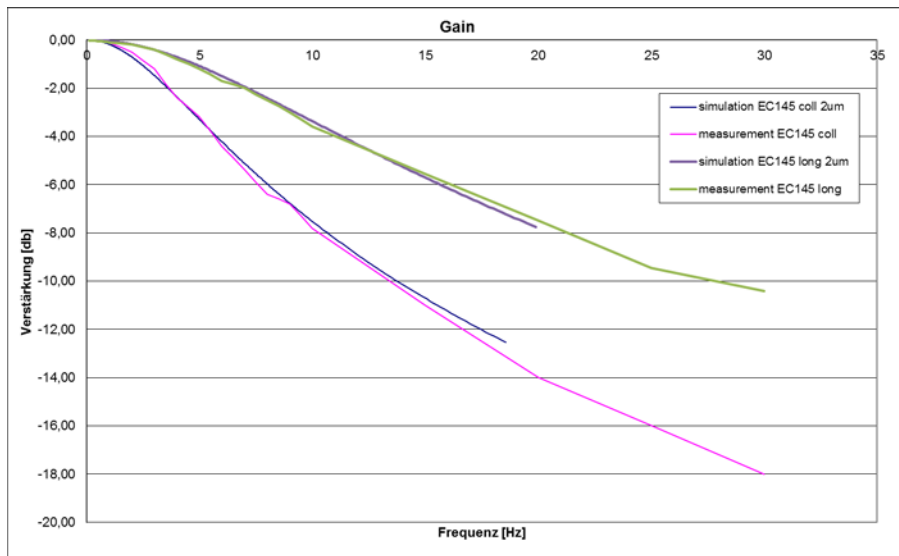
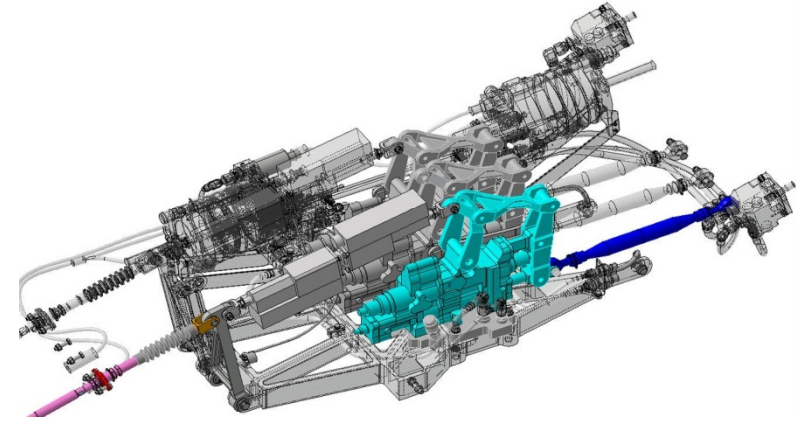
- Conservative friction estimates
- Tolerances of trim actuator breakout forces
- Secondary end stops not modeled
- Curves spring gradients = nonlinear kinematics



# Hydraulic servo actuator : phase & gain response

## Hydraulic Main Rotor Actuator of H145 (EC145)

- Different actuators for collective & longitudinal axes
- Proprietary hydraulics library (Modelon)



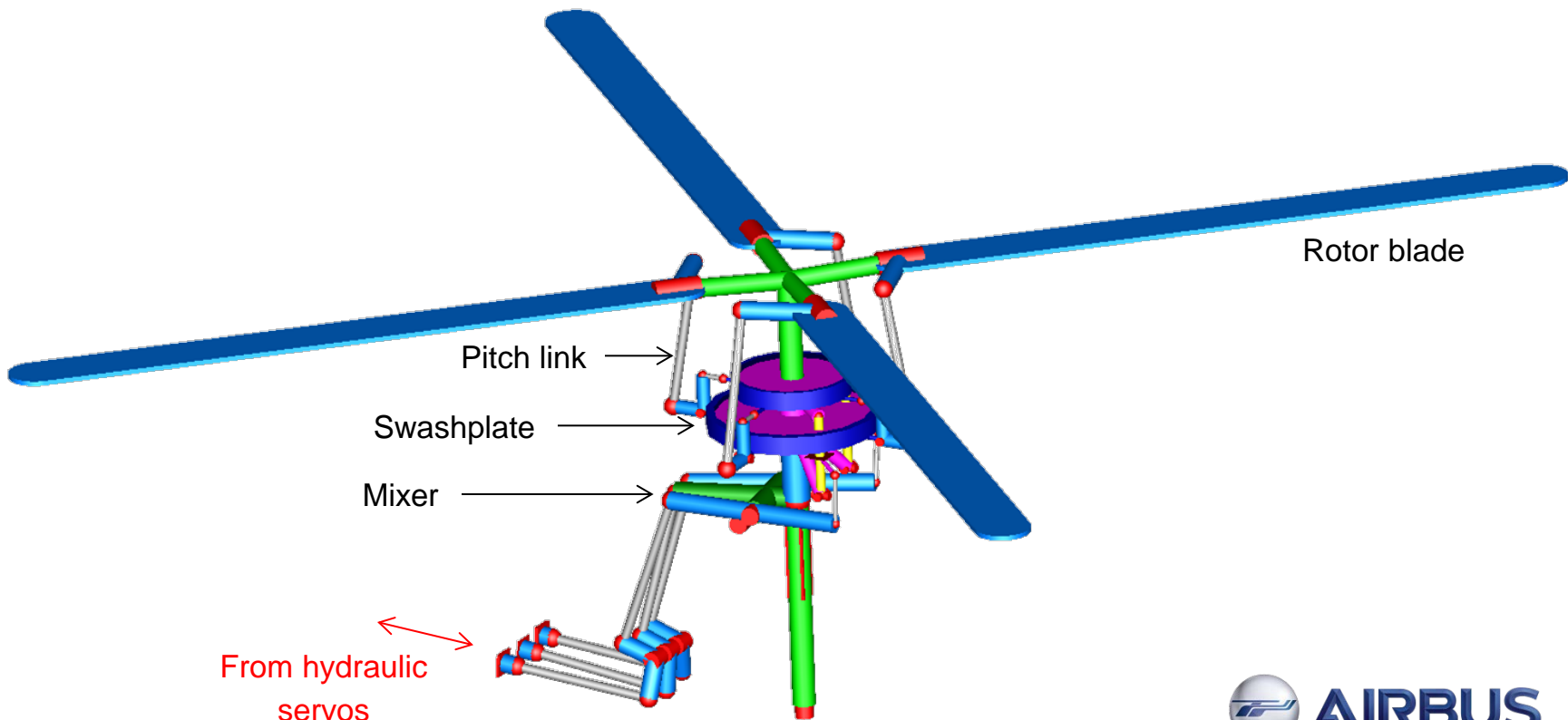
→ very good agreement between simulation and qualification measurement by supplier

# Flight Control Kinematics

Pilot stick movement prescribed for hydraulic servos

Mixing of longitudinal, lateral and collective axis → swashplate in fixed frame

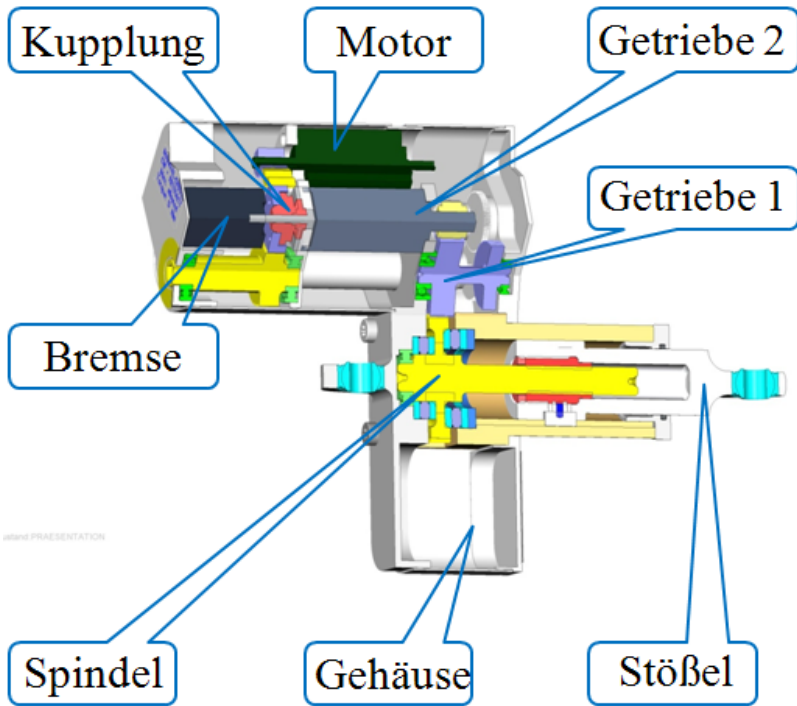
Pitch links and blades in rotating frame



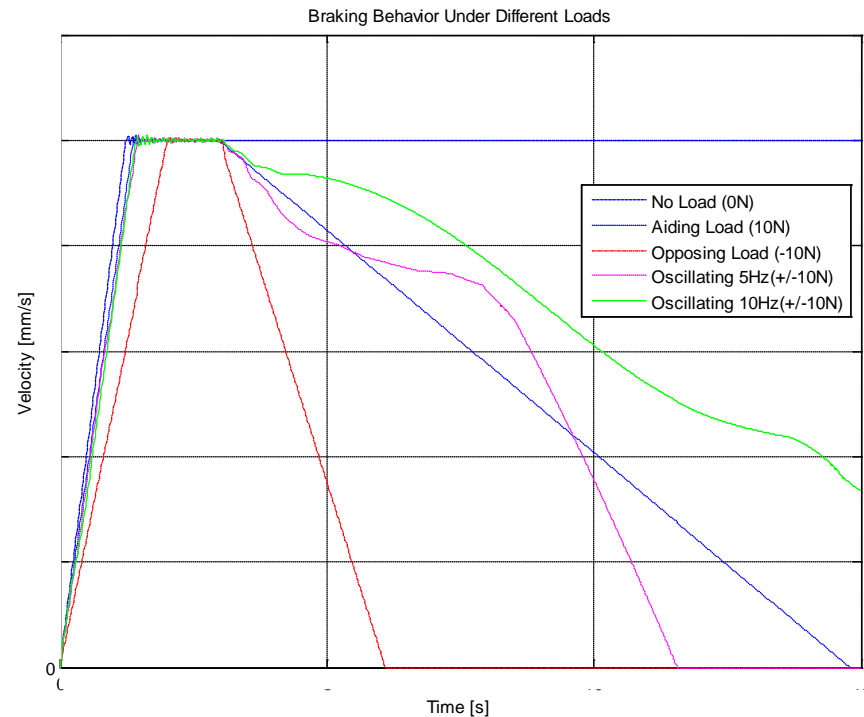
# Electro-mechanical actuator : braking travel (failure case)

Trapezoidal (ACME) screw → high friction and self-locking

In case of any detected failure → EMA is switched off → braking travel



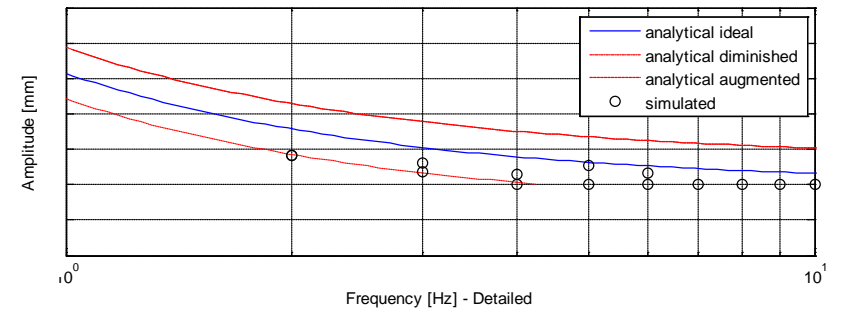
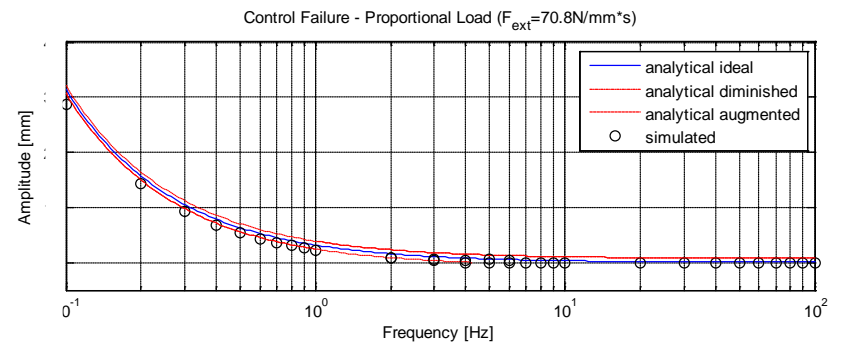
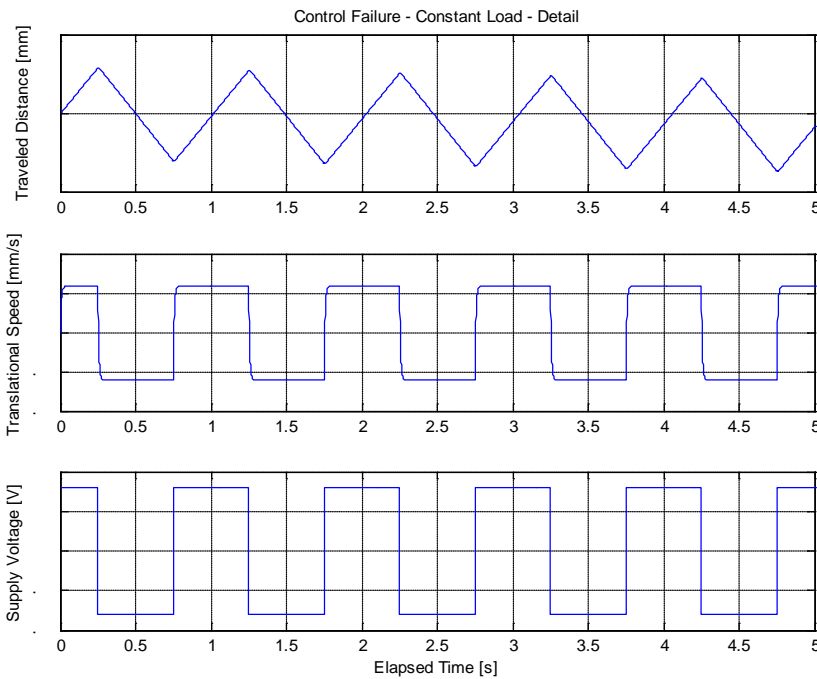
Source: EME



# Electro-mechanical actuator : oscillatory failure

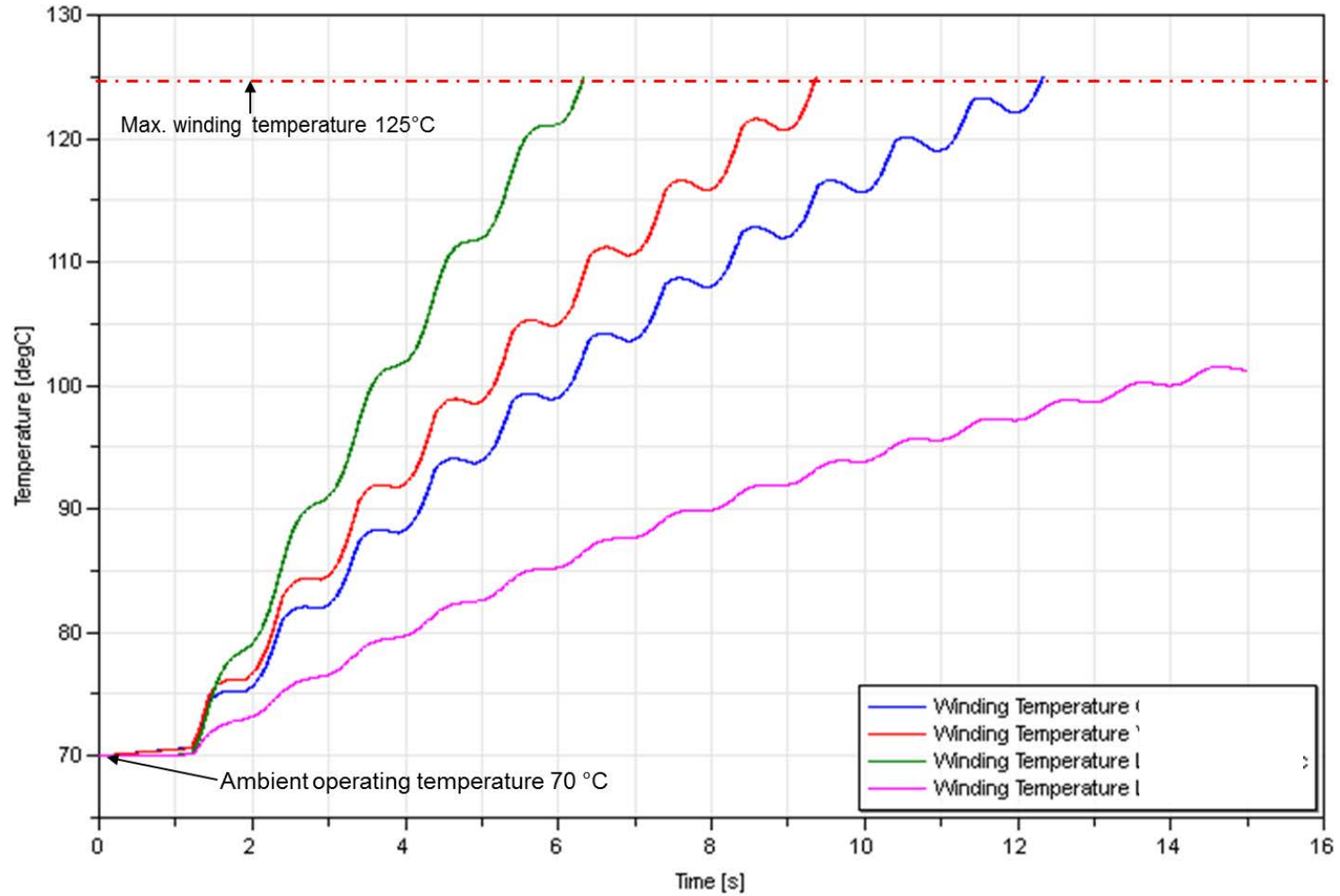
## Oscillatory failure of flight control EMA

→ prediction of oscillation amplitude as function of frequency  
 based on physical performance limitations of motor, gear & inertia





# Electro-mechanical actuator : thermal design



# „Cool“ Tools

„Linear Systems“ Modelica library: control design

- White noise
  - Resolution of DA/AD converters, e.g. 10bit or 12bit
  - Time-discrete controllers, e.g. 40Hz autopilot
- Realistic constraints for design

„Planar mechanics“ Modelica library

- Nonlinear 2D-multi-body kinematics w/o need of excessive computational resources

„Aerospace EMA“ Modelica library

- EU research project „Actuation 2015“ lead by Airbus

Modelica modeling language is **non-proprietary**

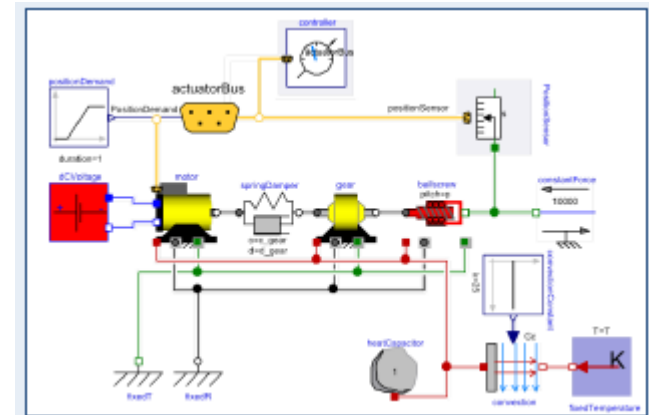
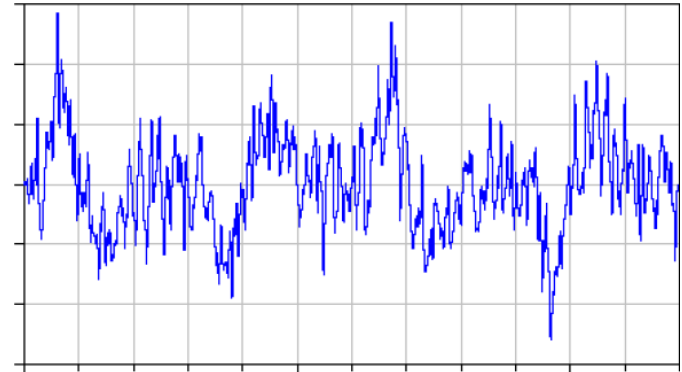
Modelica Standard Library is **open source**

Simulation tools:

Dymola (Dassault), SimulationX (ITI), MapleSim (MapleSoft), Wolfram SystemModeler,

Openmodelica.org

**Measurement or simulation ?**



# Conclusions

## Predictive Simulation of Helicopter Flight Controls

- Support feasibility studies, concept/pre-/detailed design
- Complement „real“ testing and reduce cost
- Reduce risk
- Accelerate development cycles

## V-Cycle needs to anticipate update loops for

- Improvement & re-design
- Corrective action

## Modelica

- Modeling language is non-proprietary
- Modelica Standard Library is open source
- Choice of multiple competing simulation environments

Thank you for your attention

Questions ?



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